APPLICATION FOR UNITED STATES LETTERS PATENT

FOR

COMPENSATING FOR LEAKAGE CURRENTS IN LOOP FILTER CAPACITORS IN PLLs AND THE LIKE

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Certification Under 37 CFR 1.10

Express Mail" Mailing Label No. EV140153311US	Date of Deposit <u>3/24/04</u>
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COMPENSATING FOR LEAKAGE CURRENTS IN LOOP FILTER CAPACITORS IN PLLs AND THE LIKE

BACKGROUND OF THE INVENTION

Field of the Invention

The present invention relates to electronics, and, in particular, to charge-pump phase-locked loops and other signal synthesizers having loop filters with capacitors.

Description of the Related Art

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A phase-locked loop (PLL) is a circuit that generates a periodic output signal that has a constant phase relationship with respect to a periodic input signal. PLLs are widely used in many types of measurement, microprocessor, and communication applications. One type of phase-locked loop is the charge-pump PLL, which is described in Floyd M. Gardner, "Charge-Pump Phase-Lock Loops," *IEEE Trans. Commun.*, vol. COM-28, pp. 1849-1858, Nov. 1980, the teachings of which are incorporated herein by reference.

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Fig. 1 shows a block diagram of a conventional charge-pump phase-locked loop 100. Phase detector (PD) 102 compares the phase θ_{IN} of an input signal to the phase θ_{FB} of a feedback signal and generates an error signal: either an UP signal U (when θ_{IN} leads θ_{FB}) or a DOWN signal D (when θ_{FB} leads θ_{IN}), where the width of the error signal pulse indicates the magnitude of the difference between θ_{IN} and θ_{FB} .

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Charge pump 104 generates an amount of charge q equivalent to the error signal (either U or D) from PD 102. Depending on whether the error signal was an UP signal or a DOWN signal, the charge q is either added to or subtracted from one or more capacitors in loop filter 106. In a typical implementation, loop filter 106 operates as an integrator that accumulates the net charge from charge pump 104. As shown in Fig. 1, loop filter 106 generates two inputs for voltage-controlled oscillator (VCO) 108: a low-gain input V_{CTRL} and a high-gain input V_{BG} . A voltage-controlled oscillator is a device that generates a periodic output signal (F_{OUT} in Fig. 1), whose frequency is a function of the VCO input voltages V_{CTRL} and V_{BG} , where the high-gain input voltage V_{BG} is used to set the center frequency during calibration and the low-gain input voltage V_{CTRL} serves as the steady-state signal path. In addition to being the output signal from PLL 100, the VCO output signal F_{OUT} is used to generate the feedback signal for PD 102.

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Optional input and feedback dividers 110 and 112 may be are placed in the input and feedback paths, respectively, if the frequency of the output signal F_{OUT} is to be either a fraction or a multiple of the frequency of the input signal F_{IN} .

More information about PLLs like PLL 100 can be found in U.S. Patent No. 5,942.949, the teachings of which are incorporated herein by reference.

As described previously, although not shown in Fig. 1, the loop filters of conventional charge-pump PLLs, such as PLL 100, are implemented using capacitors. In order for such PLLs to operate properly it is important to avoid the adverse affects of gate oxide leakage currents in those loop-filter capacitors. The conventional approach to avoid the adverse affects of such leakage currents is to use capacitors in the loop filter that have relative large oxide thicknesses (e.g., 50-70 Angstroms). Unfortunately, such capacitors require relatively large areas to implement. It would be desirable to implement loop filters in charge-pump PLLs using capacitors having relatively small oxide thicknesses (e.g., 17 Angstroms) and correspondingly relatively small implementation areas.

SUMMARY OF THE INVENTION

Problems in the prior art are addressed in accordance with the principles of the present invention by a loop filter architecture for charge-pump PLLs that reduces the adverse effects of gate oxide leakage currents in the capacitors used in the loop filter without requiring the use of relatively large capacitors having relatively large oxide thicknesses.

According to one embodiment of the present invention, a signal synthesizer (e.g., a PLL) comprises a loop filter connected between a charge pump and an oscillator of the signal synthesizer to accumulate charge from the charge pump and generate at least a first control signal for the oscillator.

According to one technique for operating the signal synthesizer, the loop filter comprises a damping capacitor connected to a resistor, a matching capacitor, and sensing-and-canceling circuitry adapted to (1) drive a voltage across the matching capacitor to match a first reference voltage and (2) generate, based on a first current associated with driving the voltage across the matching capacitor, a second current applied to the damping capacitor to compensate for leakage current in the damping capacitor.

According to another technique for operating the signal synthesizer, the loop filter comprises a resistor, a damping capacitor connected at a first node to the resistor, a transconductor capacitor connected to generate the first control signal for the oscillator, and a digital gm path adapted to (1) digitally accumulate differences between a reference voltage and a voltage at the first node and (2) generate a first gm output signal based on the accumulated differences, wherein the first gm output signal is applied to the transconductor capacitor.

Although not required, the two techniques can be combined in a single implementation.

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BRIEF DESCRIPTION OF THE DRAWINGS

Other aspects, features, and advantages of the present invention will become more fully apparent from the following detailed description, the appended claims, and the accompanying drawings in which like reference numerals identify similar or identical elements.

Fig. 1 shows a block diagram of a conventional charge-pump phase-locked loop;

Fig. 2 shows a high-level block diagram of a clock/data recovery (CDR) circuit, according to one embodiment of the present invention;

Fig. 3 shows a schematic diagram of the charge pump and the loop filter of the PLL of Fig. 2;

Fig. 4 shows a schematic diagram of the charge pump and the loop filter of the PLL of Fig. 2, in which the effect of gate leakage current in capacitor C1 is represented by parasitic resistor R_{PARA} ;

Fig. 5 shows a schematic diagram of the charge pump and the loop filter of Fig. 2, according to one embodiment of the present invention;

Fig. 6 shows a schematic diagram of a PLL, according to another embodiment of the present invention; and

Fig. 7 shows a schematic diagram of a PLL, according to yet another embodiment of the present invention.

DETAILED DESCRIPTION

Fig. 2 shows a high-level block diagram of a clock/data recovery (CDR) circuit 200, according to one embodiment of the present invention. CDR circuit 200 has analog front end (AFE) 202, phase detector / data recovery (PD/DR) circuitry 204, deserializer 206, and charge-pump PLL 208. PLL 208, which includes reference phase/frequency detector 210, charge pump 212, loop filter 214, multi-phase VCO 216, and feedback dividers 218, has the same basic architecture of PLL 100 of Fig. 1. In one implementation, VCO 216 is a four-stage differential ring oscillator generating eight output phases of CMOS logic levels. As such, VCO 216 runs at 1/4 of the known data rate, and a feedback divider of 4 or 5 allows for training to a local reference clock at 1/16 or 1/20 of the incoming data rate.

The purpose of CDR circuit 200 is to recover data encoded in a received analog input signal. In particular, AFE 202 provides line termination impedance and adds some gain to the input signal, PD/DR circuitry 204 recovers the data from the input signal based on a multi-phase clock signal F_{OUT} generated by VCO 216 of PLL 208, and deserializer 206 merges the recovered data to generate parallel output data (e.g., 16-bit or 20-bit words) for further processing downstream.

In order for PD/DR circuitry 204 to operate properly, the clock signal F_{OUT} generated by PLL 208 should have an appropriate frequency and be sufficiently synchronized with the data encoded in the input signal. To provide that frequency matching and phase synchronization, charge pump 212 receives UP

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and DN signals 220 from reference phase/frequency detector (PFD) 210 (when PLL 208 is operated in its "lock to reference" mode) and UP and DN signals 222 from PD/DR circuitry 204 (when PLL 208 is operated in its "lock to data" mode).

At a certain level, CDR circuit 200 could be said to have effectively two different phase-locked loops. One such loop is labeled in Fig. 2 and referred to herein as PLL 208, in which PFD 210 provides the UP/DN signals to charge pump 212. This loop is in phase lock during the "lock to reference" mode. The other loop also includes charge pump 212, loop filter 214, and VCO 216, but instead of relying on PFD 210, this loop relies on PD/DR 204 to generate the UP/DN signals for charge pump 212. This other loop is in phase lock during the "lock to data" mode.

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During the "lock to reference" mode, PFD 210 compares the phase of the feedback signal from feedback dividers 218 with the phase of a local reference clock signal F_{REF} to generate UP and DN pulses 220, which are varied in width according to the magnitude of the detected phase error. During this mode, the high-gain input signal V_{BG} is used to set the center frequency of VCO 216.

During the "lock to data" mode, PD/DR circuitry 204 uses an "Alexander" or bang-bang phase detector to compare the phase of the PLL output clock signal F_{OUT} to the phase of the input signal in order to generate phase information (i.e., UP/DOWN pulses 222) that is applied to charge pump 212 of PLL 208. The phase information from PD/DR circuitry 204 is a one-bit quantization of the actual incoming phase error and is used by charge pump 212 to put a fixed amount of charge onto the loop filter for each update. More information on Alexander phase detectors can be found in J.D.H. Alexander, "Clock Recovery from Random Binary Signals," *Electronic Letters*, October 1975, the teachings of which are incorporated herein by reference.

In either "lock to reference" or "lock to data" mode, the polarity of the charge pulse is determined by the polarity of the incoming phase error. The UP/DN pulses from PD/DR circuitry 204 and PFD 210 enable VCO 216 to generate a PLL output clock signal F_{OUT} having an appropriate frequency and phase. In "lock to reference" mode, the output of VCO 216 is phase- and frequency-locked to the reference frequency F_{REF} , which is close to but not necessarily equal to an integer scaling of the input data rate. This mode is used during system start-up to get the operating frequency of the VCO sufficiently close to an integer scaling of the data rate. Thus, it is within the pull-range of PD/DR 204, which has no embedded frequency detector, and phase-lock to the data can be obtained when the system is switched from the "lock to reference" mode to the "lock to data" mode.

Fig. 3 shows a schematic diagram of charge pump 212 and loop filter 214 of PLL 208 of Fig. 2. Charge pump 212 puts either a positive or a negative current onto loop filter 214 for an amount of time determined from the width of each received UP/DN pulse. The width of the pulse multiplied by the

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magnitude of the current determines the amount of charge injected into loop filter 214. This packet of charge charges a parasitic capacitor (not shown) and also flows through resistor R1, charging capacitor C1 (also referred to as "the damping capacitor"). The long-term voltage on capacitor C1 is summed with the voltage across resistor R1 to determine the low-gain input voltage V_{CTRL} applied to VCO 216 of Fig. 2.

Transconductor cell Gm generates -- and injects onto capacitor C3 (also referred to as the "transconductor capacitor") -- a current that is proportional to the difference between the voltage on capacitor C1 and a reference voltage V_{REF} . The voltage on capacitor C3 is adjusted, via the negative feedback action of PLL 208 (in which, for example, the PLL feedback loop from VCO 216 to PFD 210 drives the low-gain input voltage V_{CTRL} to lock the loop), until the voltage across capacitor C1 is equal to reference voltage V_{REF} . (Note that PD/DR 204 can also generate UP/DN signals for charge pump 212.) Capacitor C3 integrates the current from transconductor cell Gm to set the center frequency of VCO 216 based on the high-gain input voltage V_{BG} . While V_{BG} settles to a final value, V_{CTRL} is continuously updated to maintain phase lock.

Gate Leakage Current at the Damping Capacitor

If significant gate leakage currents are associated with the damping capacitor C1, then the performance of CDR circuit 200 of Fig. 2 will typically be degraded in two ways. The first is the movement of one integrator off of the origin, where the resulting frequency of the pole can possibly be so large as to affect loop stability. This occurs because the presence of gate leakage is equivalent to placing a resistor in parallel with capacitor C1. If this parasitic resistor R_{PARA} is not several orders of magnitude larger than resistor R1, then the frequency of the pole can be quite large. If the pole frequency is large relative to the closed-loop -3dB frequency of either the PLL employing PFD 206 (i.e., PLL 208) or the PLL employing PD/DR 204 (i.e., the "other loop" of Fig. 2), then a loss of phase margin can occur.

Fig. 4 shows a schematic diagram of charge pump 212 and loop filter 214 of PLL 208 of Fig. 2, in which the effect of gate leakage current in capacitor C1 is represented by parasitic resistor R_{PARA} .

The input impedance Z(s) as seen by the charge pump is given by Equation (1) as follows:

$$Z(s) = \frac{\left(R_{PARA} + R_{1}\right) + sR_{PARA}R_{1}C_{1}}{s\left(R_{PARA} + R_{1}\right)C_{2} + s^{2}R_{PARA}R_{1}C_{1}C_{2} + 1 + sR_{PARA}C_{1}},$$
(1)

where C_2 (not shown in Fig. 4) is the parasitic capacitance of node V_{CTRL} . In the limit, as the parasitic resistance R_{PARA} goes to infinity, the impedance Z(s) may be represented by Equation (2) as follows:

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$$Z(s) = \frac{\left(R_{1} + \frac{1}{sC_{1}}\right)}{sC_{2}\left(R_{1} + \frac{1}{sC_{2}}\right)},$$
(2)

where the magnitude of C_1 is preferably much greater than (e.g., at least 100 times) the magnitude of C_2 , in order to keep the loop stable.

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In a typical implementation, parasitic resistor R_{PARA} will have a minimum value of about 100 Kohms, while resistor R1 will have a maximum value of about 12 Kohms. Since the parasitic resistor is (at the very least) almost an order of magnitude larger than resistor R1, the movement of the integrator off of the origin is expected to be small. As such, the change in phase margin resulting from gate leakage currents should be negligible and the parasitic (i.e., gate leakage) resistor should have minimal impact on loop stability, in either the "lock to reference" mode or the "lock to data" mode. It should be noted that the charge-pump output resistance (not shown) has a similar effect and, in most designs, also has a negligible effect on stability.

The second way in which the performance of CDR circuit 200 may be degraded in the presence of gate leakage currents on the loop-filter damping capacitor C1 is by the creation of static phase offset. The dc leakage current through capacitor C1 needs to be supplied by charge pump 212. This can only be done by having a net difference between the UP and DN signals, as averaged over time. This difference results in static phase offset. This undesirable phase offset is created by the PLL's negative feedback and will typically increase the bit error rate (BER) of the data recovery process because the PD/DR circuitry 204 will no longer be sampling the data at the center of the data "eye." For example, a capacitor C1 having a parasitic resistance R_{PARA} of about 100 Kohms will have a leakage current of about 5 microamps with a nominal 0.5 volts across it, which will produce a significant static phase offset for a nominal charge-pump current of 20 microamps and will typically result in bit errors. A 17-Angstrom capacitor, which has a leakage current of about 1.6 microamps, will produce a smaller static phase offset, which can also result in bit errors, if the data rate is high enough. One skilled in the art will recognize that the direct relation between the magnitude of the leakage current and the resulting static phase offset is a complicated function of the exact PD used, the amount of incoming phase jitter and inter-symbol interference on the data stream, as well as the loop dynamics and the amount of random noise generated in the various components.

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Thus, while gate leakage currents in the loop-filter damping capacitor C1 do not appear to affect stability, they can introduce enough static phase offset to prevent desired levels of CDR performance.

Gate Leakage Current at the Transconductor Capacitor

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As described previously, transconductor cell Gm of Fig. 3 has its current integrated onto a capacitor C3 in order to effectively set the center frequency of the oscillator. If transconductor capacitor C3 suffers from gate leakage, then the effective output resistance of transconductor cell Gm is lowered, reducing the dc gain of the integrator. In order to supply the current to this parasitic resistance and maintain the desired output voltage, a non-zero input could be applied to transconductor cell Gm.

Prior to accounting for gate leakage, the output resistance of transconductor cell Gm is about 5 to 10 Mohms. Reducing it to, for example, 500 Kohms would involve an order of magnitude reduction. Further, the gain of transconductor cell Gm is typically about 2.2 microamps per volt, which means that a 0.5v input would be required to generate a 1-microamp output and thus an output voltage of 0.5v (assuming a 500-Kohm parasitic resistor). In this case, there is no linear range left (Vdd=1.0v), and transconductor cell Gm will have gone non-linear. Additionally, the maximum dc bias current in the output of transconductor cell Gm is 500 nanoamps, which is thus the maximum current that can be driven out to support a voltage across the parasitic resistor, and is half of what would otherwise be needed. Clearly, the circuit will not function properly with this amount of gate leakage.

Sensing and Canceling Gate Leakage Current at the Damping Capacitor

Fig. 5 shows a schematic diagram of charge pump 212 and loop filter 214 of Fig. 2, according to one embodiment of the present invention. In this embodiment, op amp 502 generates -- and applies to the gates of transistors 504 and 506 -- a signal that is a function of the difference between the transconductor reference voltage V_{REF} and the voltage across a matching capacitor C1'. As a result, op amp 502 forces the reference voltage V_{REF} across matching capacitor C1', while sensing the current required to do this. Scaling the current set by the size of transistor 506 by the ratio of the loop-filter damping capacitor C1 to the matching sense capacitor C1' would allow the effects of the leakage current in the damping capacitor C1 to be reduced or even canceled.

This approach allows PLL 208 of Fig. 2 to be implemented using a damping capacitor C1 having a relatively small gate oxide thickness (e.g., about 17 Angstroms) by cancelling the adverse effects of the resulting gate leakage current.

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Sensing and Canceling Gate Leakage Current at the Transconductor Capacitor

The gate leakage current in the transconductor capacitor C3 of Fig. 3 is relatively difficult to sense and cancel, because of the wide range of voltages this capacitor can have with processing variations. One approach is to scale up the gain of the transconductor cell Gm, so that it is capable of providing the current to offset leakage currents. Another approach is to replace the analog transconductor integrator with a discrete time equivalent, which has the advantage of having a voltage output that is insensitive to gate leakage currents. Yet another approach is to wrap a discrete time feedback loop around the transconductor integrator to sense and cancel the input-referred offset voltage necessary to drive the gate leakage current out of the transconductor cell.

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Fig. 6 shows a schematic diagram of a PLL 600, according to another embodiment of the present invention. PLL 600, which may be used for PLL 208 of Fig. 2, is an example of the approach in which the analog transconductor integrator is replaced with a discrete time equivalent. In particular, transconductor cell Gm of Fig. 3 is replaced by comparator 602, digital accumulator 604, and digital-to-analog (D/A) converter 606.

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In particular, comparator 602 samples and compares the voltage across damping capacitor C1 to reference voltage V_{REF} to generate a digital value, whose magnitude and sign depend on the difference between those two voltages. Accumulator 604 accumulates the digital values received from comparator 602 over time, and D/A converter 606 converts the resulting accumulated value into an analog output that gets applied to capacitor C3 to generate the analog VCO input voltage signal V_{BG} . In one implementation, D/A converter 606 functions as a voltage source generating an analog voltage signal. In another implementation, D/A converter 606 functions as a current source generating an analog current signal. When capacitor C3 is driven by a voltage source, rather than a current source, the effects of gate leakage current are moot.

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In order for the digital path to act as an integrator, the rate at which comparator 602 samples the voltage on capacitor C1 could be very low (e.g., a frequency more than three orders of magnitude less than the 3dB frequency of the closed-loop PLL) or the gain of the accumulator could be small or some appropriate combination of both relatively low sample rate and relatively small accumulator gain so that there is a low-pass filtering effect from the voltage on capacitor C1 to V_{BG} , with the corner frequency of this low-pass filter many (e.g., three or more orders of magnitude below the equivalent 3dB frequency of the closed-loop PLL). Also, capacitor C3 should filter the step response of the D/A output, with a time constant significantly below that of the closed-loop PLL response. This would ensure that a change in the output of the D/A converter is not seen as a phase ramp / frequency step at the input to the data/phase detector, which could result in bit errors. By slowing down the rate at which the D/A output voltage into

the VCO can change, the wide-band PLL loop can compensate for the changing voltage at the high-gain input to the VCO.

The particular type of comparator and where the accumulator derives its input from may vary from implementation to implementation, allowing for design-specific tradeoffs.

This approach allows PLL 600 to be implemented using a capacitor C3 having a relatively small gate oxide thickness (e.g., about 17 Angstroms) by cancelling the adverse effects of the resulting gate leakage current.

Fig. 7 shows a schematic diagram of a PLL 700, according to yet another embodiment of the present invention. PLL 700, which may be used for PLL 208 of Fig. 2, is an example of the approach in which a digital accumulator is implemented in parallel with an analog transconductor integrator. In this case, the continuous-time integrator provides the main performance, while the parallel digital accumulator is used to compensate for the gate leakage currents and any other DC leakage currents on capacitor C3. Note that, in this embodiment, the digital accumulator includes comparator 702, digital accumulator 704, and current source (Idac) 706, which converts the accumulated digital value from accumulator 704 into a current signal that is applied to capacitor C3.

According to this approach, in order for transconductor cell Gm to supply a dc current to compensate for gate leakage current in capacitor C3, a non-zero differential input is applied to the transconductor cell. By using a comparator to sense this differential input voltage and integrating the comparator output over a period of time long enough to make the loop stable, a digital word can be created. This drives Idac 706, which produces a current compensating for the gate leakage current in C3.

When the Idac output current changes, the high-gain input V_{BG} to the VCO will change as the current difference between the Idac output and the gate leakage current is integrated onto the capacitor. The main PLL feedback loop will, via phase detector (PD) and charge pump (CP), adjust the voltage at the input to the transconductor cell, so that the output current of the transconductor cell changes by an amount equal to, but opposite in sign to, the original change in the output of the Idac.

Assuming the time constant of the digital integrator is at least two orders of magnitude slower than the time constant associated with the Gm stage and capacitor C3, the entire loop should remain stable.

There are second-order effects which might need to be addressed. One is the difference between the input-referred offset of the comparator and the input-referred offset of the transconductor cell itself. One solution is to use the same differential pair for both the transconductor cell and the comparator, guaranteeing that they both see almost exactly the same input-referred offset voltage.

Another difficulty is to create an Idac whose least significant bit (LSB) is on the order of 100 nanoamps. In this case, since the polarity of the gate leakage current is known, one can use the digital

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bits to adjust the bias current in the output stage of the transconductor cell to compensate for the gate leak currents. No separate D/C converter block is required.

Another difficulty arises from the fact that, because the new path is a digital loop, the output of the Idac will dither. While it might appear that this would cause a triangular wave to appear on the voltage across capacitor C3, this is not the case. In fact, the main PLL loop, whose bandwidth is much larger, adjusts the voltage on capacitor C1 instead. The voltage on capacitor C1 is adjusted to cause the current output from the transconductor cell to compensate for the current change from the Idac. Thus, the voltage across capacitor C3 will charge slightly as the output of the Idac changes, and then settle back as the value of the voltage across capacitor C1 changes to accommodate. This ripple can be kept arbitrarily small by keeping capacitor C3 large, the LSB step size of the Idac small, or some combination of both.

In the event this ripple becomes unacceptable, because gate leakage currents are primarily a DC term, it is possible to turn the adaptation loop off after some initial period. This leaves the main transconductor cell to accommodate the residual error, and any errors created by a change in temperature from when the adaptation loop was turned off. The change in gate leakage currents with temperature needs to be small enough to be well within the linear range of the transconductor cell.

This approach allows PLL **700** to be implemented using a capacitor C3 having a relatively small gate oxide thickness (e.g., about 17 Angstroms) by cancelling the adverse effects of the resulting gate leakage current.

Although the technique for sensing and canceling the effects of gate leakage current in damping capacitor C1 shown in Fig. 5 and the techniques for sensing and canceling the effects of gate leakage current in transconductor capacitor C3 shown in Figs. 6 and 7 can be implemented separately, in a preferred embodiment, techniques for each capacitor are combined to enable both capacitors to be implemented with relatively small gate oxide thicknesses.

Although the present invention has been described in the context of phase-locked loops, the present invention can also be implemented in the context of other types of signal synthesizers, such as delay-locked loops (DLLs).

Unless explicitly stated otherwise, each numerical value and range should be interpreted as being approximate as if the word "about" or "approximately" preceded the value of the value or range.

It will be further understood that various changes in the details, materials, and arrangements of the parts which have been described and illustrated in order to explain the nature of this invention may be made by those skilled in the art without departing from the scope of the invention as expressed in the following claims.

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The use of figure numbers and/or figure reference labels in the claims is intended to identify one or more possible embodiments of the claimed subject matter in order to facilitate the interpretation of the claims. Such use is not to be construed as necessarily limiting the scope of those claims to the embodiments shown in the corresponding figures.